

UNIVERSIDAD POLITECNICA DE VALENCIA
DEPARTAMENTO DE INGENIERIA MECANICA Y DE MATERIALES

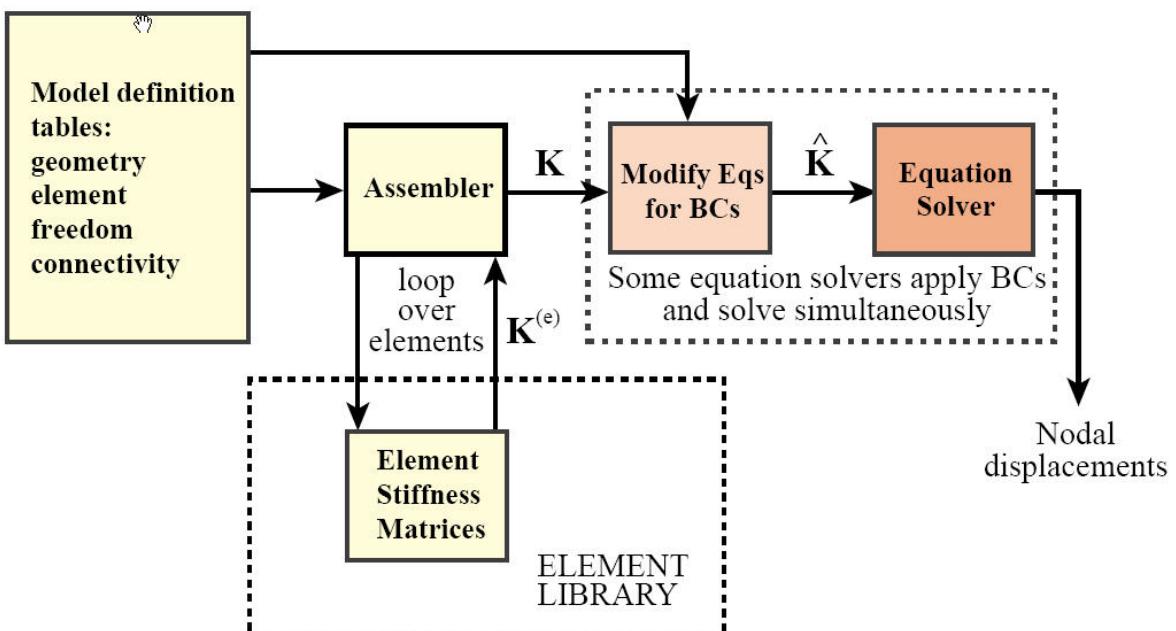
**ELEMENTOS FINITOS
(E.T.S.I.I.V)**

**FORMULACION DE ELEMENTOS FINITOS
SOLUCION DE LAS ECUACIONES**

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$$\mathbf{Ku} = \mathbf{f}$$



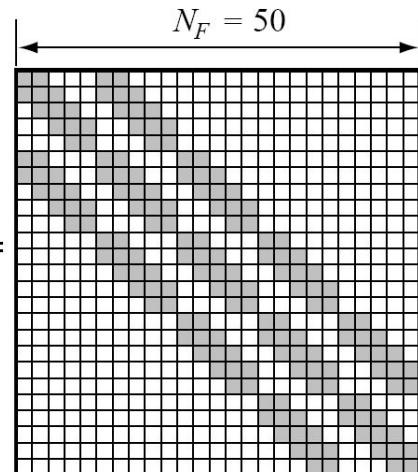
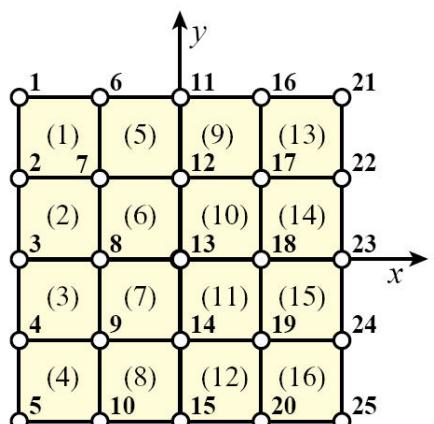
Storage and Solution Times for a Fully Stored Stiffness Matrix

Matrix order N	Storage (double prec)	Factor op. units	Factor time workstation/PC	Factor time supercomputer
10^4	800 MB	$10^{12}/6$	3 hrs	2 min
10^5	80 GB	$10^{15}/6$	4 mos	30 hrs
10^6	8 TB	$10^{18}/6$	300 yrs	3 yrs

time numbers last adjusted in 1998
to get current times divide by 10-20

As regards memory needs, a full square matrix stored without taking advantage of symmetry, requires storage for N^2 entries. If each entry is an 8-byte, double precision floating-point number, the required storage is $8N^2$ bytes. Thus, a matrix of order $N = 10^4$ would require 8×10^8 bytes or 800 MegaBytes (MB) for storage.

For large N the solution of (26.1) is dominated by the factorization of \mathbf{K} , an operation discussed in §26.2. This operation requires approximately $N^3/6$ floating point operation units. [A floating-point operation unit is conventionally defined as a (multiply,add) pair plus associated indexing and data movement operations.] Now a fast workstation can typically do 10^7 of these operations per second, whereas a supercomputer may be able to sustain 10^9 or more.

**Storage and Solution Times for a Skyline Stiffness Matrix****Assuming $B = \sqrt{N}$**

Matrix order N	Storage (double prec)	Factor op. units	Factor time workstation/PC	Factor time supercomputer
10^4	8 MB	$10^8/2$	5 sec	0.05 sec
10^5	240 MB	$10^{10}/2$	8 min	5 sec
10^6	8000 MB	$10^{12}/2$	15 hrs	8 min

time numbers last adjusted in 1998
to get current times divide by 10-20

If a skymatrix of order N can be stored in S memory locations, the ratio $B = S/N$ is called the *mean bandwidth*. If the entries are, as usual, 8-byte double-precision floating-point numbers, the storage requirement is $8NB$ bytes. The factorization of a skymatrix requires approximately $\frac{1}{2}NB^2$ floating-point operation units. In two-dimensional problems B is of the order of \sqrt{N} .

**How the Master Stiffness Equations are Stored
in a commonly used "skyline" sparse format**

**How to Mark BC on the Master Stiffness Eqs
(if you write your own solver)**

The Basic Solution Steps

**(Implementation Details will be Skipped since
Built-in Mathematica Solver will be used for
Demo Programs)**

MATRIZ DE RIGIDEZ

$$\mathbf{K} = \begin{bmatrix} & & 11 & & 13 & & & 16 \\ & & & 22 & 0 & 24 & & 0 \\ & & & & 33 & 34 & & 0 \\ & & & & & 44 & & 46 \\ & & & & & & 55 & 56 \\ & & & & & & & 66 \end{bmatrix}$$

symm

VECTOR SKYLINE

$$\mathbf{s} = \{ 11, 22, 13, 0, 33, 24, 34, 44, 55, 16, 0, 0, 46, 56, 66 \}$$

VECTOR LOCALIZACION TERMINOS DIAGONAL

$$\mathbf{p} = \{ 0, 1, 2, 5, 8, 9, 15 \}$$

VECTOR COMPLETO

$$\mathbf{S} = \{ \mathbf{p}, \mathbf{s} \}$$

$$\mathbf{S} = \{ \{ 0, 1, 2, 5, 8, 9, 15 \}, \{ 11, 22, 13, 0, 33, 24, 34, 44, 55, 16, 0, 0, 46, 56, 66 \} \}$$

Equations for which the displacement component is known or prescribed are identified by a ***negative*** diagonal location value. For example, if u_3 and u_5 are prese4ribed displacement components in the sample system,

$$\mathbf{p} : [0, 1, 2, -5, 8, -9, 15]$$

FACTORIZACION

$$\mathbf{K} = \mathbf{LDU} = \mathbf{LDL}^T = \mathbf{U}^T \mathbf{DU}$$

where \mathbf{L} is a unit lower triangular matrix, \mathbf{D} is a nonsingular diagonal matrix, and \mathbf{U} and \mathbf{L} are the transpose of each other. The original matrix is overwritten by the entries of \mathbf{D}^{-1} and \mathbf{U} .

SymmSkyMatrixFactor

SOLUCION

$$\text{Forward reduction : } \mathbf{L}\mathbf{z} = \mathbf{f},$$

$$\text{Diagonal scaling : } \mathbf{D}\mathbf{y} = \mathbf{z},$$

$$\text{Back substitution : } \mathbf{U}\mathbf{u} = \mathbf{y},$$

SymmSkyMatrixVectorSolve.