

UNIVERSIDAD POLITECNICA DE VALENCIA
DEPARTAMENTO DE INGENIERIA MECANICA Y DE MATERIALES

ELEMENTOS FINITOS
(E.T.S.I.I.V)

FORMULACION DE ELEMENTOS FINITOS
LECCION 3.- EL PROBLEMA DE TENSION PLANA

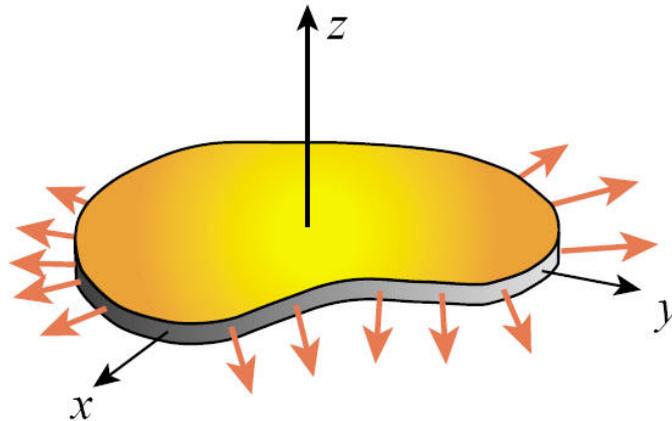
J. L. OLIVER
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Valencia, 2005

Plate in Plane Stress



Thickness dimension
or transverse dimension



Inplane dimensions: in x,y plane

Plane Stress Physical Assumptions

Plate is flat and has a symmetry plane (the midplane)

All loads and support conditions are midplane symmetric

Thickness dimension is much smaller than inplane dimensions

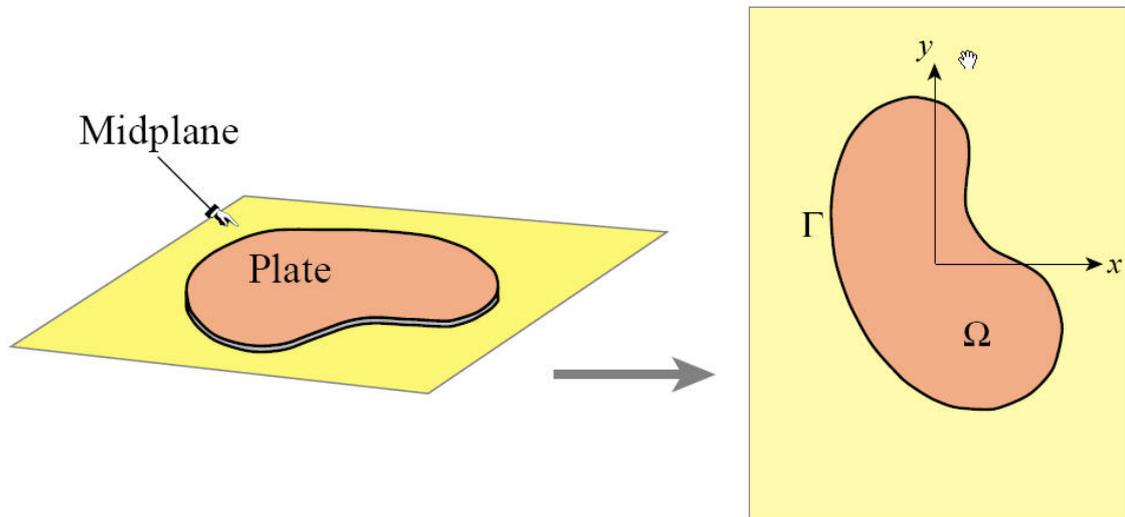
Inplane displacements, strains and stresses uniform through thickness

Transverse stresses σ_{zz} , σ_{xz} and σ_{yz} negligible

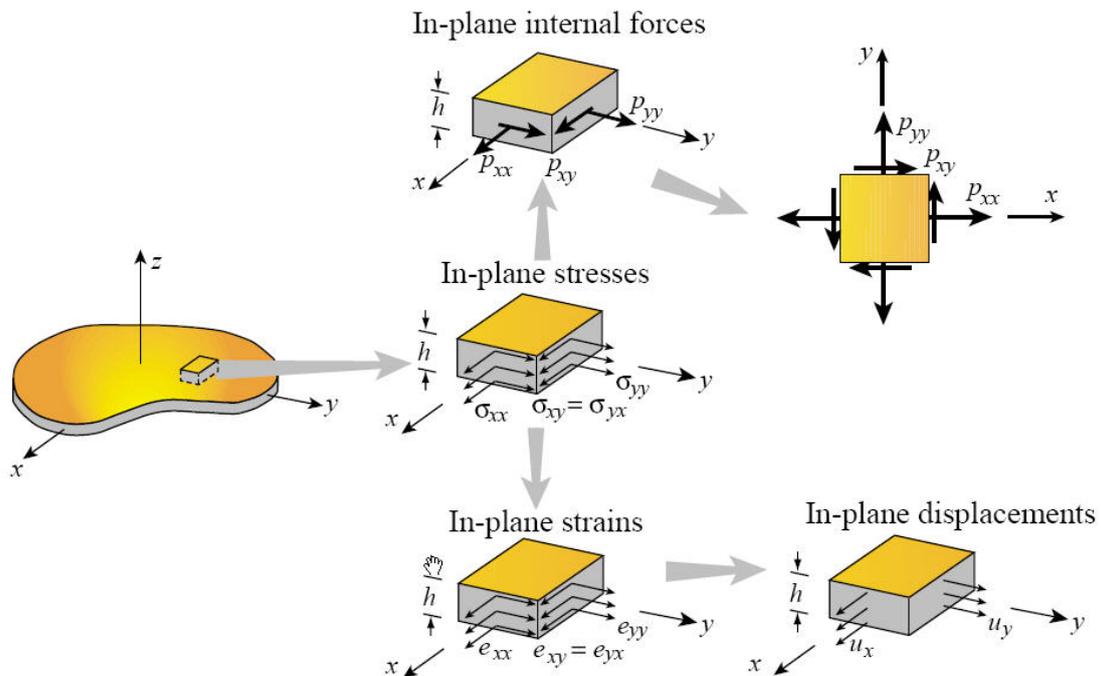
Unessential but used in this course:

Plate fabricated of homogeneous material through thickness

Mathematical Idealization as a Two Dimensional Problem



Notation for stresses, strains, forces, displacements



The Plane Stress Problem

Given:

geometry

material properties

wall fabrication (thickness only for homogeneous plates)

applied body forces

boundary conditions:

prescribed boundary forces or tractions

prescribed displacements

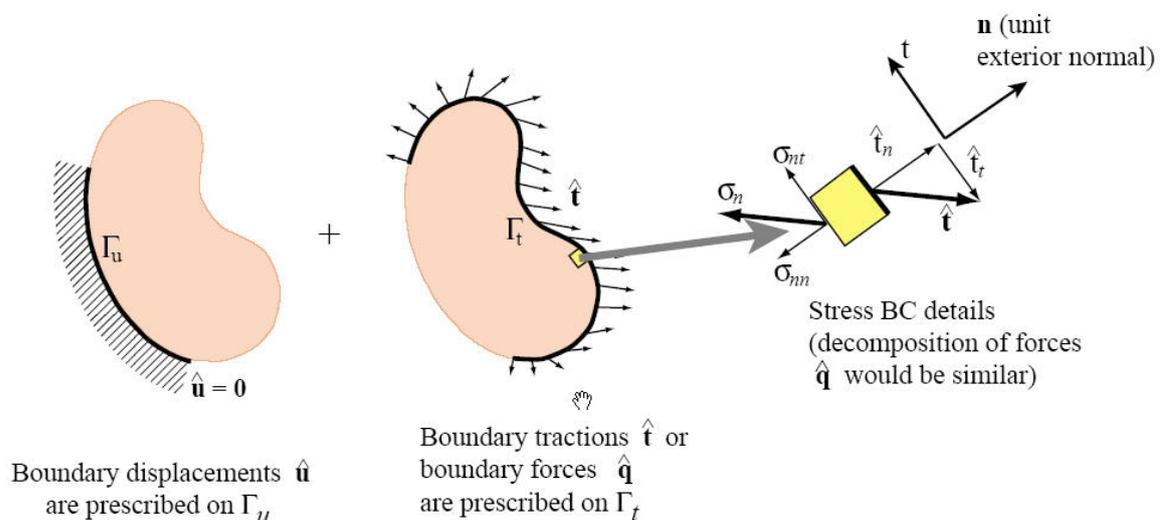
Find:

inplane displacements

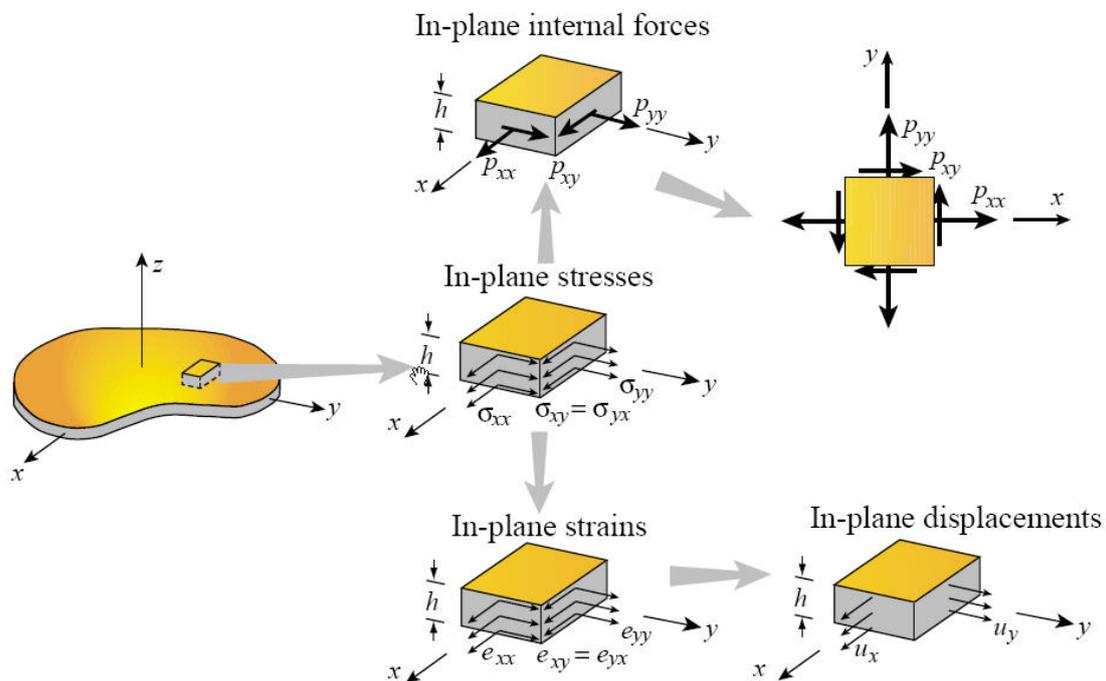
inplane strains

inplane stresses and/or internal forces

Plane Stress Boundary Conditions



Notation for stresses, strains, forces, displacements



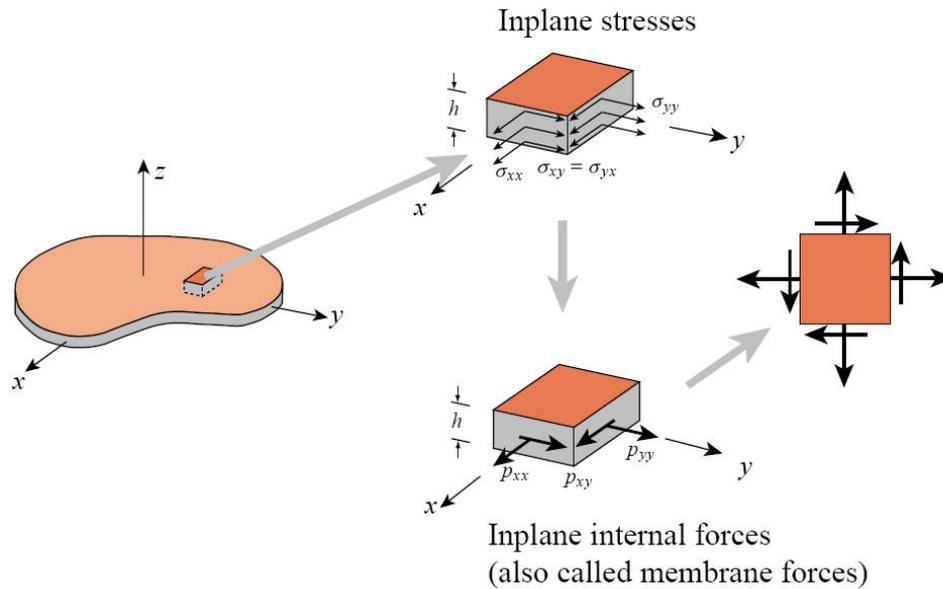
Matrix Notation for Internal Fields

$$\mathbf{u}(x, y) = \begin{bmatrix} u_x(x, y) \\ u_y(x, y) \end{bmatrix} \quad \text{displacements}$$

$$\mathbf{e}(x, y) = \begin{bmatrix} e_{xx}(x, y) \\ e_{yy}(x, y) \\ 2e_{xy}(x, y) \end{bmatrix} \quad \text{strains}$$

$$\boldsymbol{\sigma}(x, y) = \begin{bmatrix} \sigma_{xx}(x, y) \\ \sigma_{yy}(x, y) \\ \sigma_{xy}(x, y) \end{bmatrix} \quad \text{stresses}$$

Inplane Forces are Obtained by Stress Integration Through Thickness



$$p_{xx} = \sigma_{xx}h, \quad p_{yy} = \sigma_{yy}h, \quad p_{xy} = \sigma_{xy}h.$$

Governing Plane Stress Elasticity Equations in Matrix Form

$$\begin{bmatrix} e_{xx} \\ e_{yy} \\ 2e_{xy} \end{bmatrix} = \begin{bmatrix} \partial/\partial x & 0 \\ 0 & \partial/\partial y \\ \partial/\partial y & \partial/\partial x \end{bmatrix} \begin{bmatrix} u_x \\ u_y \end{bmatrix}$$

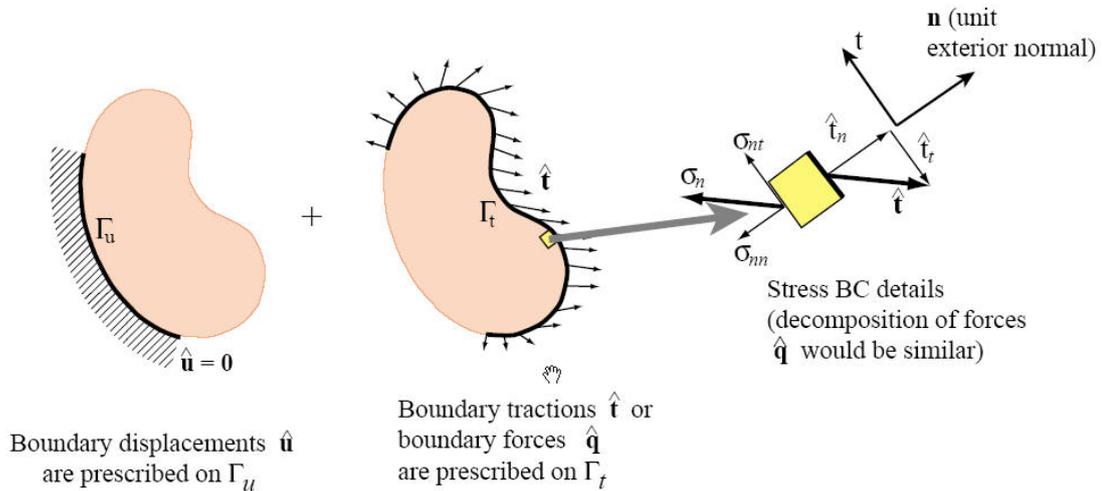
$$\begin{bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{xy} \end{bmatrix} = \begin{bmatrix} E_{11} & E_{12} & E_{13} \\ E_{12} & E_{22} & E_{23} \\ E_{13} & E_{23} & E_{33} \end{bmatrix} \begin{bmatrix} e_{xx} \\ e_{yy} \\ 2e_{xy} \end{bmatrix}$$

$$\begin{bmatrix} \partial/\partial x & 0 & \partial/\partial y \\ 0 & \partial/\partial y & \partial/\partial x \end{bmatrix} \begin{bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{xy} \end{bmatrix} + \begin{bmatrix} b_x \\ b_y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

or

$$\mathbf{e} = \mathbf{D}\mathbf{u} \quad \boldsymbol{\sigma} = \mathbf{E}\mathbf{e} \quad \mathbf{D}^T \boldsymbol{\sigma} + \mathbf{b} = \mathbf{0}$$

Plane Stress Boundary Conditions

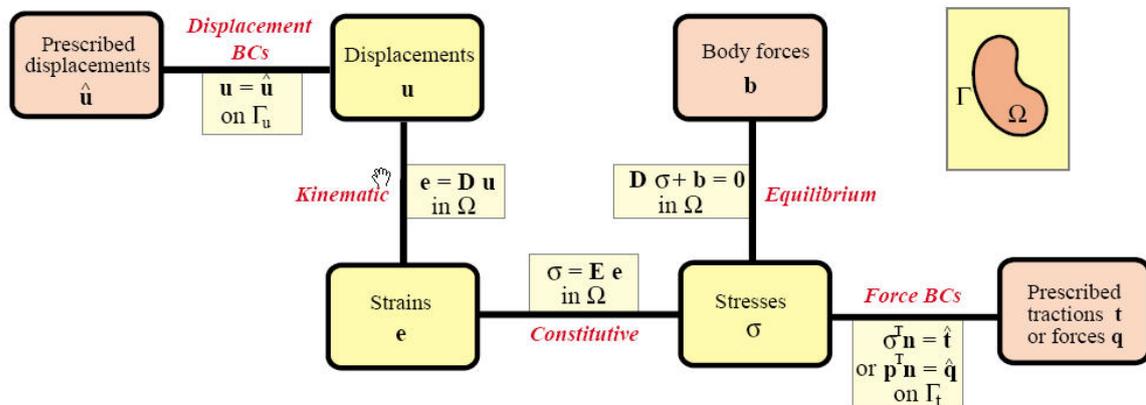


$$\mathbf{u} = \hat{\mathbf{u}}.$$

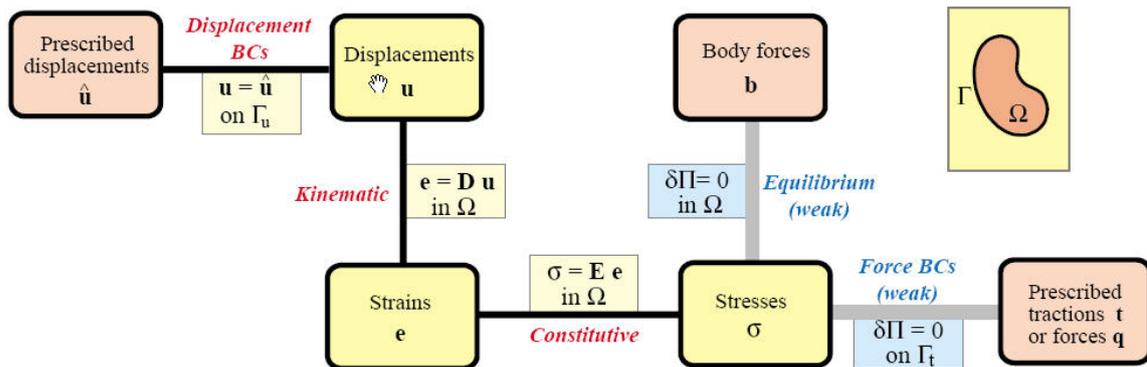
$$\sigma_n = \hat{\mathbf{t}}.$$

$$\mathbf{p}_n = \hat{\mathbf{q}}.$$

Strong Form Tonti Diagram of Plane Stress Governing Equations



TPE-Based Weak Form Diagram of Plane Stress Governing Equations



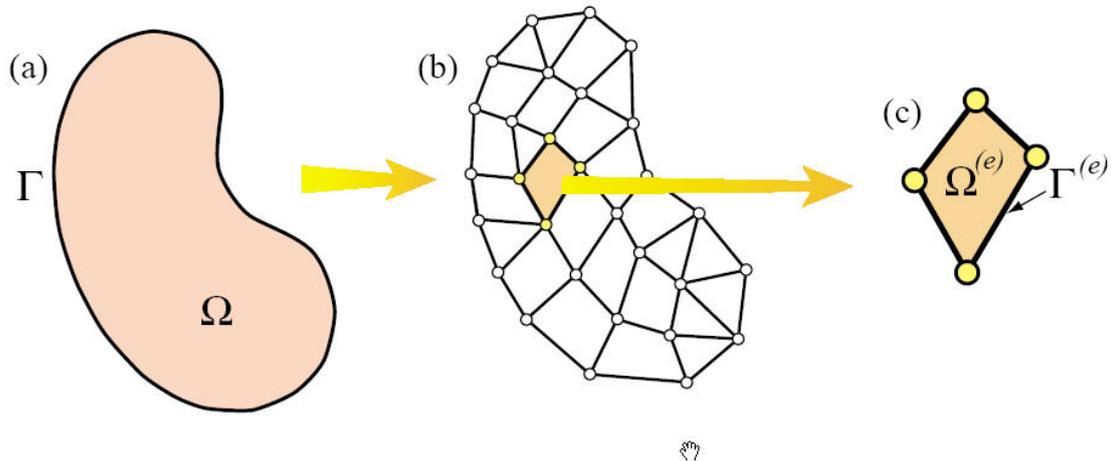
Total Potential Energy of Plate in Plane Stress

$$\Pi = U - W$$

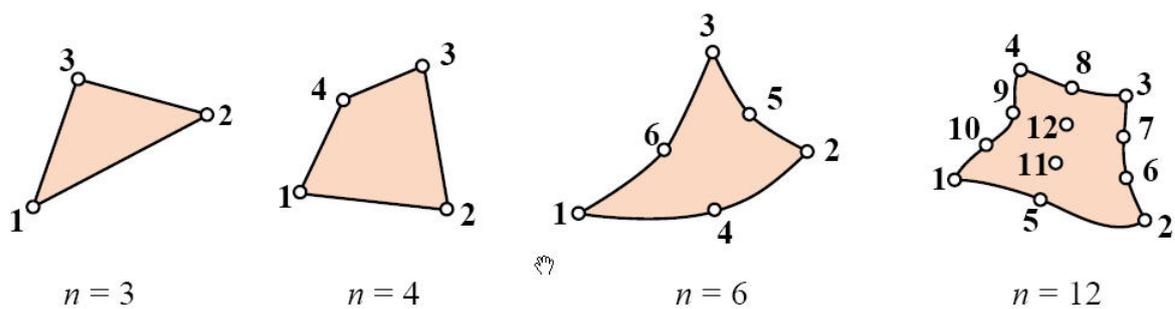
$$U = \frac{1}{2} \int_{\Omega} h \boldsymbol{\sigma}^T \mathbf{e} d\Omega = \frac{1}{2} \int_{\Omega} h \mathbf{e}^T \mathbf{E} \mathbf{e} d\Omega$$

$$W = \int_{\Omega} h \mathbf{u}^T \mathbf{b} d\Omega + \int_{\Gamma_t} h \mathbf{u}^T \hat{\mathbf{t}} d\Gamma$$

Discretization into Plane Stress Finite Elements

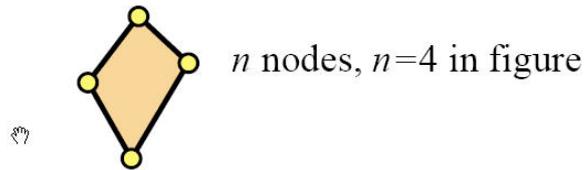


Plane Stress Element Geometries and Node Configurations



$$\mathbf{u}^{(e)} = [u_{x1} \quad u_{y1} \quad u_{x2} \quad \dots \quad u_{xn} \quad u_{yn}]^T.$$

Constructing a Displacement Assumed Element



Node displacement vector:

$$\mathbf{u}^{(e)} = [u_{x1} \quad u_{y1} \quad u_{x2} \quad \dots \quad u_{xn} \quad u_{yn}]^T$$

Displacement interpolation

$$\mathbf{u}(x, y) = \begin{bmatrix} u_x(x, y) \\ u_y(x, y) \end{bmatrix} = \begin{bmatrix} N_1^{(e)} & 0 & N_2^{(e)} & 0 & \dots & N_n^{(e)} & 0 \\ 0 & N_1^{(e)} & 0 & N_2^{(e)} & \dots & 0 & N_n^{(e)} \end{bmatrix} \mathbf{u}^{(e)}$$

$$= \mathbf{N} \mathbf{u}^{(e)}$$

\mathbf{N} is called the **shape function matrix**

Requirements on Finite Element Shape Functions

Interpolation Conditions:

N_i takes on value 1 at node i , 0 at all other nodes

Continuity (intra- and inter-element) and Completeness Conditions

are covered later in the course (Chs. 18-19)

Element Construction (cont'd)

Differentiate the displacement interpolation wrt x, y
to get the strain-displacement relation

$$\mathbf{e}(x, y) = \begin{bmatrix} \frac{\partial N_1^{(e)}}{\partial x} & 0 & \frac{\partial N_2^{(e)}}{\partial x} & 0 & \dots & \frac{\partial N_n^{(e)}}{\partial x} & 0 \\ 0 & \frac{\partial N_1^{(e)}}{\partial y} & 0 & \frac{\partial N_2^{(e)}}{\partial y} & \dots & 0 & \frac{\partial N_n^{(e)}}{\partial y} \\ \frac{\partial N_1^{(e)}}{\partial y} & \frac{\partial N_1^{(e)}}{\partial x} & \frac{\partial N_2^{(e)}}{\partial y} & \frac{\partial N_2^{(e)}}{\partial x} & \dots & \frac{\partial N_n^{(e)}}{\partial y} & \frac{\partial N_n^{(e)}}{\partial x} \end{bmatrix} \mathbf{u}^{(e)} = \mathbf{B} \mathbf{u}^{(e)}$$

\mathbf{B} is called the **strain-displacement matrix**

$$\mathbf{B} = \mathbf{D}\mathbf{N}^{(e)}$$

$$\boldsymbol{\sigma} = \mathbf{E} \mathbf{e} = \mathbf{E}\mathbf{B}\mathbf{u}^{(e)}$$

$$\delta \Pi^{(e)} = \delta U^{(e)} - \delta W^{(e)} = 0.$$

$$U^{(e)} = \frac{1}{2} \int_{\Omega^{(e)}} h \boldsymbol{\sigma}^T \mathbf{e} d\Omega^{(e)} = \frac{1}{2} \int_{\Omega^{(e)}} h \mathbf{e}^T \mathbf{E} \mathbf{e} d\Omega^{(e)}$$

$$W^{(e)} = \int_{\Omega^{(e)}} h \mathbf{u}^T \mathbf{b} d\Omega^{(e)} + \int_{\Gamma^{(e)}} h \mathbf{u}^T \hat{\mathbf{t}} d\Gamma^{(e)}$$

$$\mathbf{u} = \mathbf{N}\mathbf{u}^{(e)}$$

$$\mathbf{e} = \mathbf{B}\mathbf{u}^{(e)}$$

$$\boldsymbol{\sigma} = \mathbf{E}\mathbf{e}$$

Element Construction (cont'd)

Element total potential energy

$$\Pi^{(e)} = \frac{1}{2} \mathbf{u}^{(e)T} \mathbf{K}^{(e)} \mathbf{u}^{(e)} - \mathbf{u}^{(e)T} \mathbf{f}^{(e)}$$

Element stiffness matrix

$$\mathbf{K}^{(e)} = \int_{\Omega^{(e)}} h \mathbf{B}^T \mathbf{E} \mathbf{B} d\Omega^{(e)}$$

Consistent node force vector

$$\mathbf{f}^{(e)} = \int_{\Omega^{(e)}} h \mathbf{N}^T \mathbf{b} d\Omega^{(e)} + \int_{\Gamma^{(e)}} h \mathbf{N}^T \hat{\mathbf{t}} d\Gamma^{(e)}$$

body force

surface force

The calculation of the entries of $\mathbf{K}^{(e)}$ and $\mathbf{f}^{(e)}$ for several elements of historical or practical interest is described in subsequent Chapters.

EXERCISE 14.1

[A:25] Suppose that the structural material is isotropic, with elastic modulus E and Poisson's ratio ν . The in-plane stress-strain relations for plane stress ($\sigma_{zz} = \sigma_{xz} = \sigma_{yz} = 0$) and plane strain ($e_{zz} = e_{xz} = e_{yz} = 0$) as given in any textbook on elasticity, are

$$\begin{aligned} \text{plane stress: } \begin{bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{xy} \end{bmatrix} &= \frac{E}{1-\nu^2} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & \frac{1-\nu}{2} \end{bmatrix} \begin{bmatrix} e_{xx} \\ e_{yy} \\ 2e_{xy} \end{bmatrix}, \\ \text{plane strain: } \begin{bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{xy} \end{bmatrix} &= \frac{E(1-\nu)}{(1+\nu)(1-2\nu)} \begin{bmatrix} 1 & \frac{\nu}{1-\nu} & 0 \\ \frac{\nu}{1-\nu} & 1 & 0 \\ 0 & 0 & \frac{1-2\nu}{2(1-\nu)} \end{bmatrix} \begin{bmatrix} e_{xx} \\ e_{yy} \\ 2e_{xy} \end{bmatrix}. \end{aligned} \quad (\text{E14.1})$$

Show that the constitutive matrix of plane strain can be formally obtained by replacing E by a fictitious modulus E^* and ν by a fictitious Poisson's ratio ν^* in the plane stress constitutive matrix and suppressing the stars. Find the expression of E^* and ν^* in terms of E and ν . This device permits "reusing" a plane stress FEM program to do plane strain, as long as the material is isotropic.

EXERCISE 14.2

[A:25] In the finite element formulation of near incompressible isotropic materials (as well as plasticity and viscoelasticity) it is convenient to use the so-called *Lamé constants* λ and μ instead of E and ν in the constitutive equations. Both λ and μ have the physical dimension of stress and are related to E and ν by

$$\lambda = \frac{\nu E}{(1+\nu)(1-2\nu)}, \quad \mu = G = \frac{E}{2(1+\nu)}. \quad (\text{E14.2})$$

Conversely

$$E = \frac{\mu(3\lambda + 2\mu)}{\lambda + \mu}, \quad \nu = \frac{\lambda}{2(\lambda + \mu)}. \quad (\text{E14.3})$$

Substitute (E14.3) into (E14.1) to express the two stress-strain matrices in terms of λ and μ . Then split the stress-strain matrix \mathbf{E} of plane strain as

$$\mathbf{E} = \mathbf{E}_\mu + \mathbf{E}_\lambda \quad (\text{E14.4})$$

in which \mathbf{E}_μ and \mathbf{E}_λ contain only μ and λ , respectively, with \mathbf{E}_μ diagonal and $E_{\lambda 33} = 0$. This is the Lamé or $\{\lambda, \mu\}$ splitting of the plane strain constitutive equations, which leads to the so-called \mathbf{B} -bar formulation of near-incompressible finite elements.³ Express \mathbf{E}_μ and \mathbf{E}_λ also in terms of E and ν .

For the plane stress case perform a similar splitting in which where \mathbf{E}_λ contains only $\bar{\lambda} = 2\lambda\mu/(\lambda + 2\mu)$ with $E_{\lambda 33} = 0$, and \mathbf{E}_μ is a diagonal matrix function of μ and $\bar{\lambda}$.⁴ Express \mathbf{E}_μ and \mathbf{E}_λ also in terms of E and ν .

EXERCISE 14.5

[A:25=5+5+15] A plate is in linearly elastic plane stress. It is shown in courses in elasticity that the internal strain energy density stored per unit volume is

$$\mathcal{U} = \frac{1}{2}(\sigma_{xx}e_{xx} + \sigma_{yy}e_{yy} + \sigma_{xy}e_{xy} + \sigma_{yx}e_{yx}) = \frac{1}{2}(\sigma_{xx}e_{xx} + \sigma_{yy}e_{yy} + 2\sigma_{xy}e_{xy}). \quad (\text{E14.5})$$

- (a) Show that (E14.5) can be written in terms of strains only as

$$\mathcal{U} = \frac{1}{2}\mathbf{e}^T \mathbf{E} \mathbf{e}, \quad (\text{E14.6})$$

and hence justify (14.13).

- (b) Show that (E14.5) can be written in terms of stresses only as

$$\mathcal{U} = \frac{1}{2}\boldsymbol{\sigma}^T \mathbf{C} \boldsymbol{\sigma}, \quad (\text{E14.7})$$

where $\mathbf{C} = \mathbf{E}^{-1}$ is the elastic compliance (strain-stress) matrix.

- (c) Suppose you want to write (E14.5) in terms of the extensional strains $\{e_{xx}, e_{yy}\}$ and of the shear stress $\sigma_{xy} = \sigma_{yx}$. This is known as a mixed representation. Show that

$$\mathcal{U} = \frac{1}{2} \begin{bmatrix} e_{xx} \\ e_{yy} \\ \sigma_{xy} \end{bmatrix}^T \begin{bmatrix} A_{11} & A_{12} & A_{13} \\ A_{12} & A_{22} & A_{23} \\ A_{13} & A_{23} & A_{33} \end{bmatrix} \begin{bmatrix} e_{xx} \\ e_{yy} \\ \sigma_{xy} \end{bmatrix}, \quad (\text{E14.8})$$

and explain how the entries A_{ij} can be calculated⁵ in terms of the elastic moduli E_{ij} .